## Math 308N

Your Name

## Your Signature

Student ID #


## **Honor Statement**

I agree to complete this exam without unauthorized assistance from any person, materials, or device.

Signature: \_\_\_\_\_

- Turn off all cell phones, pagers, radios, mp3 players, and other similar devices.
- This exam is closed book. You may use one  $8.5'' \times 11''$  sheet of handwritten notes (both sides OK). Do not share notes. No photocopied materials are allowed.
- Calculators are not allowed.
- In order to receive credit, you must **show all of your work**. If you do not indicate the way in which you solved a problem, you may get little or no credit for it, even if your answer is correct.
- If you need more room, use the backs of the pages and indicate that you have done so.
- Raise your hand if you have a question.
- This exam has 6 pages, plus this cover sheet. Please make sure that your exam is complete.

Question	Points	Score
1	20	
2	10	
3	10	
4	10	
Spicy Bonus	6	
Total	50	

1. (20 points) Indicate whether the given statement is true or false (2 pts) and give justification as to why it is true or false(2 pts).

a) [4 pts] Let  $\{\vec{u_1}, \vec{u_2}, \vec{u_3}\}$  be a linearly independent set in  $\mathbb{R}^3$ , then the set  $\{c\vec{u_1}, c\vec{u_2}, c\vec{u_3}\}$  is linearly independent, for all scalars  $c \neq 0$ .

b) [4 pts] There exists a linear transformation  $T : \mathbb{R}^3 \to \mathbb{R}$  such that

$$T\left( \begin{bmatrix} 1\\0\\1 \end{bmatrix} \right) = 3 \text{ and } T\left( \begin{bmatrix} 4\\0\\4 \end{bmatrix} \right) = 9$$

c) [4 pts] If  $\vec{u_1}, \vec{u_2}$ , and  $\vec{v}$  are vectors in  $\mathbb{R}^3$ , and  $\vec{v}$  is in span{ $\vec{u_1}, \vec{u_2}$ }, then { $\vec{u_1}, \vec{u_2}, \vec{v}$ } can never span  $\mathbb{R}^3$ .

Give an example of each of the following. If it is not possible write "NOT POSSIBLE". No justification is needed if it is not possible.

d) [2 pt] A linear transformation  $T : \mathbb{R}^2 \to \mathbb{R}^2$ , given by  $T(\vec{\mathbf{x}}) = A\vec{\mathbf{x}}$ , which reflects the unit square about the *x*-axis. (Note: Take the unit square to lie in the first quadrant. Giving the matrix of *T*, if it exists, is a sufficient answer).

e) [2 pt] A set of 4 vectors in  $\mathbb{R}^3$  that spans  $\mathbb{R}^3$  and is linearly **dependent**.

f) [2 pt] 3 linearly independent vectors  $\vec{u_1}, \vec{u_2}, \vec{u_3}$  satisfying the equation  $2\vec{u_1} + 3\vec{u_2} - 4\vec{u_3} = \vec{0}$ .

g) [2 pts] A **homogeneous** linear system with strictly more variables than equations, having exactly one solution.

- 2. (10 points) Consider the following linear system with *a* and *b* nonzero constants.
  - $\begin{cases} x_1 3x_2 + x_3 = 4\\ 2x_1 8x_3 = -2\\ -6x_1 + 6x_2 + ax_3 = b \end{cases}$

a) [5 pts] For what values of a and b does the system have infinitely many solutions?

a) [5 pts] Give an example of *a* and *b* where the system has exactly one solution.

- 3. (10 points) Let  $T : \mathbb{R}^3 \to \mathbb{R}^2$  be given by  $T\left( \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} -x_1 + 3x_2 + 2x_3 \\ 4x_1 12x_2 8x_3 \end{bmatrix}$ .
  - a) [3pts] Determine the matrix associated to T. That is, find the matrix A such that  $T(\vec{x}) = A\vec{x}$ .

b) [3 pts] Is T one-to one? Explain your answer.

c) [4pts] Is T onto? If not, find a vector not in the range of T.

4. (10 points) a) [4 pts] Let 
$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$
,  $\mathbf{u}_2 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$ ,  $\mathbf{u}_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$ . Show that the set  $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  spans  $\mathbb{R}^3$ .

b) [4 pts] Express the vector 
$$\mathbf{v} = \begin{bmatrix} 3 \\ 5 \\ 11 \end{bmatrix}$$
 as a linear combination of the vectors from the previous part.

c) [2 pts] Let  $T : \mathbb{R}^3 \to \mathbb{R}^2$  be a linear transformation such that

$$T(\mathbf{u}_1) = \begin{bmatrix} 1\\ 3 \end{bmatrix}, T(\mathbf{u}_2) = \begin{bmatrix} 2\\ 0 \end{bmatrix}, T(\mathbf{u}_3) = \begin{bmatrix} 1\\ -1 \end{bmatrix}$$

Compute  $T(\mathbf{v})$  (where  $\mathbf{v}$  is the same vector as in part b).

## **Super Spicy Bonus Question**

5. (6 points) a) [4pts] Let  $f(x) = ax^2 + bx + c$  denote an arbitrary polynomial of degree 2, with constants a, b, and c. To each such polynomial, associate the vector

$$ax^2 + bx + c \leftrightarrow \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Let *T* be the linear transformation given by T(f(x)) = f'(x). In other words, *T* is the linear transformation that eats a degree 2 polynomial and spits out its derivative (Yes it is linear!). Find the matrix corresponding to *T*. (Hint: Remember that if we are given a linear transformation *T* as above, its matrix is completely determined by  $T(\mathbf{e}_i)$ , i.e.  $T(\mathbf{x}) = A\mathbf{x}$  where  $A = [T(\mathbf{e}_1) \ T(\mathbf{e}_2) \ T(\mathbf{e}_3)]$ 

b) [2 pts] Is T one-to one? Is it onto? Explain your answer.